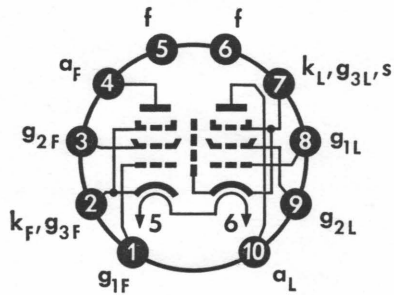
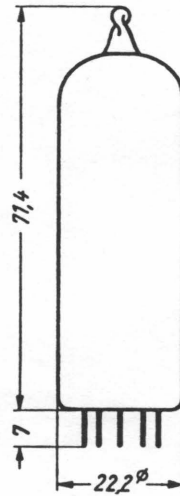


Sockelschaltbild
Base connection



Dekal

max. Abmessungen
max. dimensions



Gewicht · Weight
max. 20 g

Wenn notwendig, muß gegen Herausfallen der Röhre aus der Fassung Vorsorge getroffen werden.
Special precautions must be taken to prevent the tube from becoming dislodged.

Netzröhre für GW-Heizung
indirekt geheizt
Serienleistung

DC-AC-Heating
indirectly heated
connected series

TELEFUNKEN

PFL 200

**Pentode/Endpentode
Power pentode**

Vorläufige technische Daten · Tentative data

**Pentode für gesteuerte Schwundregelung, Impulsabtrennstufen,
Ton-ZF-Verstärker. Endpentode für Video-Endstufen.**

Pentode for gated AGC, pulse separators, audio IF amplifiers.
Power pentode for video power stages.

U_f	ca. 17	V
I_f	300	mA

Normierte Anheizzeit · Normalize heating-up time

Meßwerte · Measuring values

Pentode (System: F)

U_a	150	V
U_{g2}	150	V
U_{g1}	-2,1	V
I_a	10	mA
I_{g2}	3	mA
S	8,5	mA/V
R_i	150	k Ω
$\mu_{g2/g1}$	36	

Endpentode (System: L)

U_a	170	V
U_{g2}	170	V
U_{g1}	-2,6	V
I_a	30	mA
I_{g2}	7	mA
S	21	mA/V
R_i	33	k Ω
$\mu_{g2/g1}$	35	

Betriebswerte · Typical operation

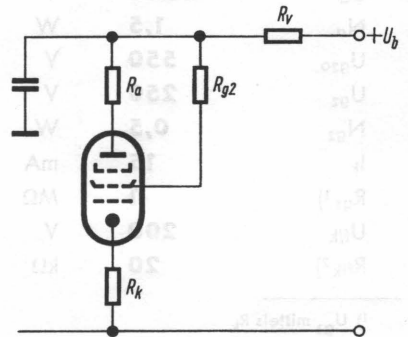
als Video-Endröhre · as video-power stage

System: L

U_b	220	V
R_v	560	Ω
R_a	2	k Ω
R_{g2}	1	k Ω
R_k	6,8	Ω
$U_{in\ sp\ sp}^1$	(-0,4... -3) + (-3... -4)	V
$U_{out\ sp\ sp}$	80 + 20	V

$$\frac{S_{-3}}{S_{-0,4}} \quad 2) \quad \geq 0,7$$

$$\frac{S_{-4}}{S_{-0,4}} \quad 2) \quad \geq 0,5$$



1) Momentanwerte von Bildinhalt und Synchronimpuls.

Momentary value of picture information and sync. pulse.

2) Verhältnis der dynamischen Steilheiten an den Aussteuerungsgrenzen für Bildinhalt und Synchronimpuls als Maß für die Verzerrung.

Ratio of dynamic transconductances at modulation limits for picture content and sync. pulse as measure for distortion.



Kapazitäten · Capacitances

System: F

C_e	10	pF
C_a	10,5	pF
$C_{g1/a}$	0,14	pF
$C_{g1/f}$	< 0,15	pF

System: L

C_e	13	pF
C_a	7	pF
$C_{g1/a}$	0,1	pF

zwischen System: F und System: L

between system: F and system: L

$C_{aF/aL}$	< 0,15	pF
$C_{g1F/g1L}$	< 0,01	pF
$C_{aF/g1L}$	< 0,005	pF
$C_{aL/g1F}$	< 0,1	pF

Nennwert-Grenzdaten · Design centre ratings

System: F

U_{a0}	± 550	V
U_a	± 250	V
N_a	1,5	W
U_{g20}	550	V
U_{g2}	250	V
N_{g2}	0,5	W
I_k	15	mA
$R_{g1}^{1)}$	1	MΩ
$U_{f/k}$	200	V
$R_{f/k}^{2)}$	20	kΩ

System: L

U_{a0}	550	V
U_a	250	V
N_a	5	W
U_{g20}	550	V
U_{g2}	250	V
$N_{g2}^{3)}$	2,5	W
$I_k^{3)}$	60	mA
$R_{g1}^{1)}$	0,5	MΩ
$U_{f/k}$	200	V
$R_{f/k}$	20	kΩ

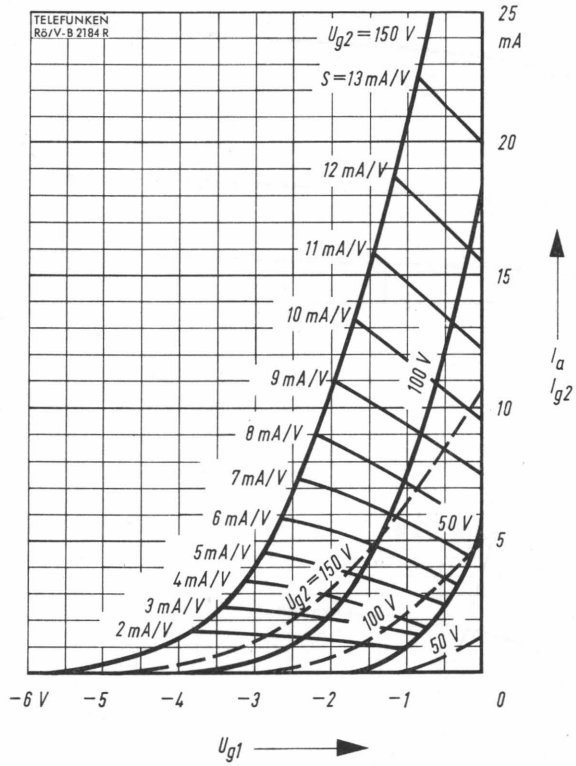
1) U_{g1} mittels R_k
 U_{g1} by R_k

2) max. 50 kΩ für getastete Schwundregelung.
max. 50 kΩ for gated AGC

3) Bei fehlendem Eingangssignal darf während max. 1 Stunde N_{g2} auf max. 3,2 W und I_k auf max. 85 mA ansteigen.

When no input signal is present N_{g2} may rise to max. 3.2 W and I_k to max. 85 mA during max. 1 hour.





$$I_a, I_{g2} = f(U_{g1})$$

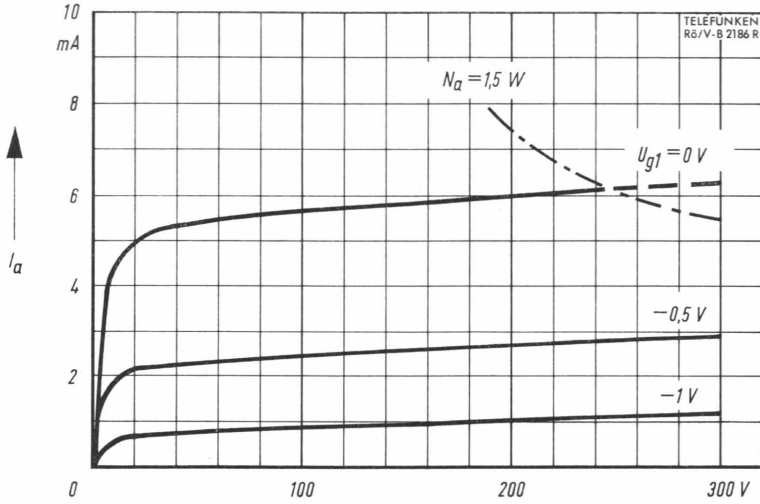
$$U_a = 150 \text{ V}$$

$U_{g2}, S = \text{Parameter}$

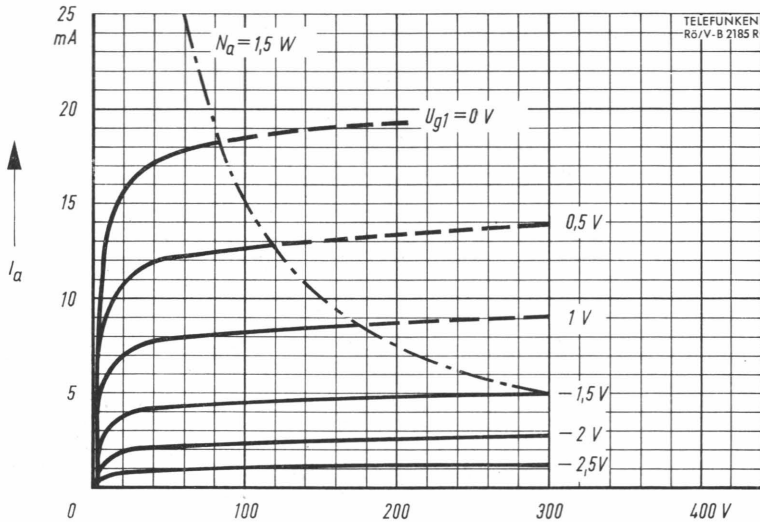
— I_a - - - I_{g2}

Pentode (F-System)





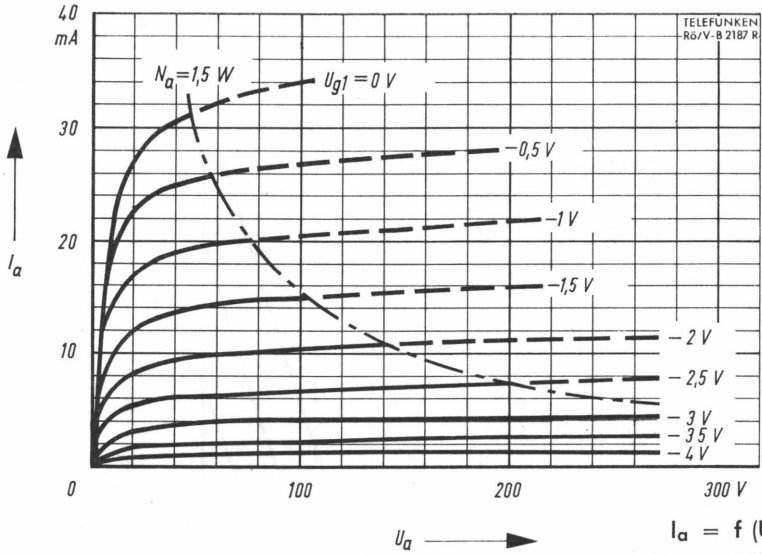
$I_a = f(U_a)$
 $U_{g2} = 50 \text{ V}$
 $U_{g1} = \text{Parameter}$



$I_a = f(U_a)$
 $U_{g2} = 100 \text{ V}$
 $U_{g1} = \text{Parameter}$

Pentode (F-System)

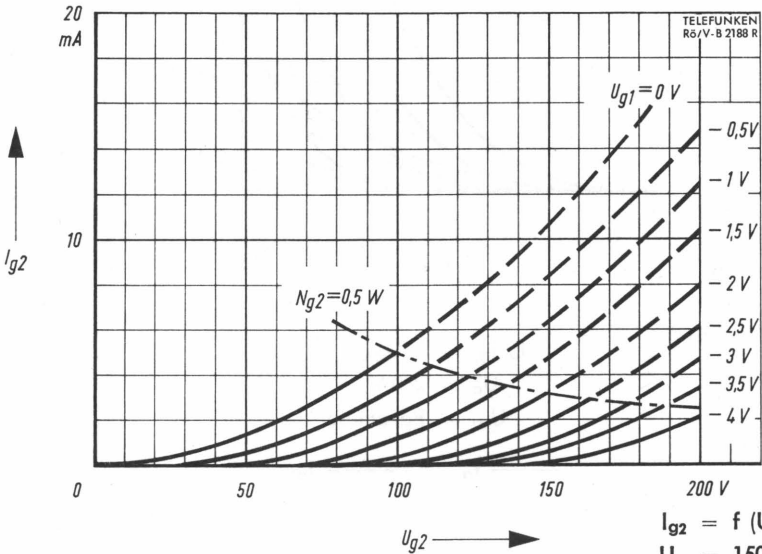




$$I_a = f(U_a)$$

$$U_{g2} = 150 \text{ V}$$

$$U_{g1} = \text{Parameter}$$



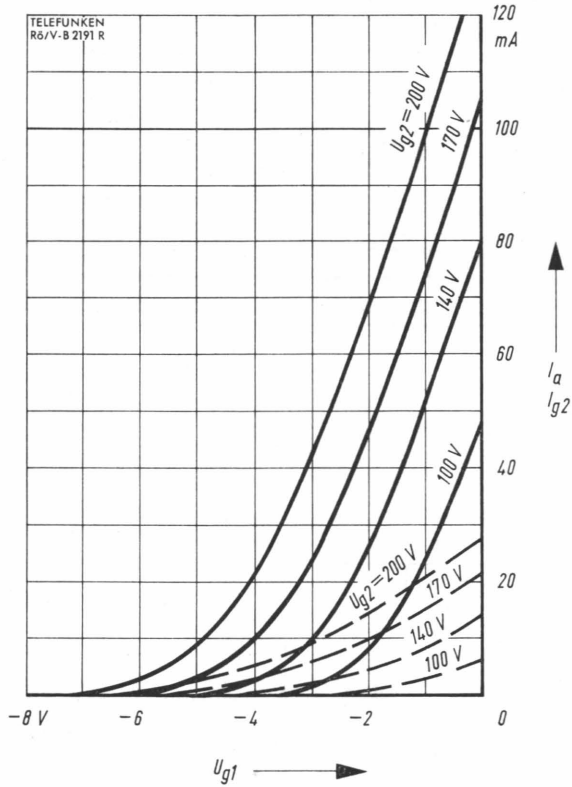
$$I_{g2} = f(U_{g2})$$

$$U_a = 150 \text{ V}$$

$$U_{g1} = \text{Parameter}$$

Pentode (F-System)





$$I_a, I_{g2} = f(U_{g1})$$

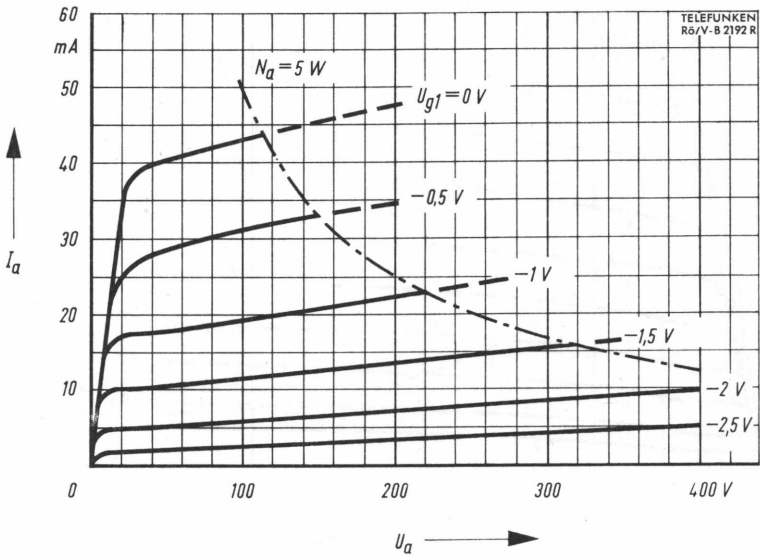
$$U_a = 200\text{ V}$$

$$U_{g2} = \text{Parameter}$$

— I_a - - - - I_{g2}

Endpentode (L-System)

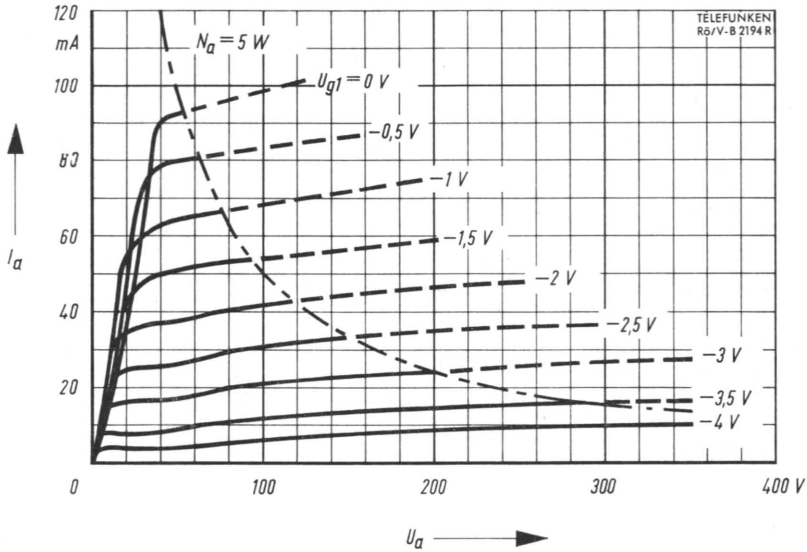




$I_a = f(U_a)$
 $U_{g2} = 100\text{ V}$
 $U_{g1} = \text{Parameter}$

Endpentode (L-System)





$I_a = f(U_a)$
 $U_{g2} = 170 V$
 $U_{g1} = \text{Parameter}$

Endpentode (L-System)

